Introduction to Linear Models

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Outline for Introduction to Linear Models

Based on Love and Irizarry, Data Analysis for the Life [Sciences](https://leanpub.com/dataanalysisforthelifesciences), Chapter 5

- **Multiple linear regression**
	- *Continuous and categorical predictors*
	- *Interactions*
- **Model formulae**
- **Design matrix**
- **Analysis of Variance**

Introduction to Linear Models

Example: friction of spider legs

Wolff & Gorb, Radial [arrangement](http://www.nature.com/articles/srep01101) of Janus-like setae permits \blacksquare friction control in spiders, *Sci. Rep.* 2013.

- **(A)** Barplot showing total claw tuft area of the corresponding \blacksquare legs.
- **(B)** Boxplot presenting friction coefficient data illustrating \blacksquare median, interquartile range and extreme values.

Example: friction of spider legs

- Are the pulling and pushing friction coefficients different? \blacksquare
- Are the friction coefficients different for the different leg pairs? \blacksquare
- Does the difference between pulling and pushing friction \blacksquare coefficients vary by leg pair?

Example: friction of spider legs

table(spider\$leg,spider\$type)

summary(spider)

What are linear models?

- Linear models model a response variable Y_i as a linear combination of predictors, plus randomly distributed noise.
- **Which of the following are examples of linear models?**

1. $y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$ 2. $y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \varepsilon_i$ 3. $y_i = \beta_0 + \beta_1 x_i + \times 2^{\beta_2 x_i} + \varepsilon_i$

Where: $i = 1, ..., N$

Assumption: $\varepsilon_i \stackrel{iid}{\thicksim} N(0,\sigma^2_\epsilon)$

What are linear models?

The following are examples of linear models:

- 1. $y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$ (simple linear regression)
- 2. $y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \varepsilon_i$ (quadratic regression)

Multiple linear regression model

- **Example 1** Linear models can have any number of predictors
- Systematic part of model:

 $E[y|x] = \beta_0 + \beta_1x_1 + \beta_2x_2 + \ldots + \beta_px_p$

- $E[y|x]$ is the expected value of y given x
- y is the outcome, response, or dependent variable
- x is the vector of predictors / independent variables
- α_p are the individual predictors or independent variables
- β_p are the regression coefficients

Multiple linear regression model

Random part of model:

 $y_i = E[y_i|x_i] + \epsilon_i$

Assumptions of linear models: $\epsilon_i \stackrel{iid}{\thicksim} N(0,\sigma^2_{\epsilon})$

- **Normal distribution**
- **Mean zero at every value of predictors**
- Constant variance at every value of predictors \blacksquare
- **Values that are statistically independent**

Continuous predictors

- **Coding:** as-is, or may be scaled to unit variance (which results in *adjusted* regression coefficients)
- **Interpretation for linear regression:** An increase of one unit of the predictor results in this much difference in the continuous outcome variable

Binary predictors (2 levels)

- **Coding:** indicator or dummy variable (0-1 coding)
- **Interpretation for linear regression:** the increase or decrease in average outcome levels in the group coded "1" , compared to the reference category ("0")
- *e.g.* $E(y|x) = \beta_0 + \beta_1 x$
- where $x = \{ 1$ if push friction, 0 if pull friction $\}$

Multilevel categorical predictors (ordinal or nominal)

- **Coding:** $K 1$ dummy variables for K -level categorical variable
- Comparisons with respect to a reference category, *e.g.* L1:
	- L2={1 if 2^{nd} leg pair, 0 otherwise},
	- L3={1 if 3^{nd} leg pair, 0 otherwise},
	- L4={1 if 4^{th} leg pair, 0 otherwise}.
- R re-codes factors to dummy variables automatically.
- Note that factors can be *ordered* or *unordered*

Model formulae in R

Model formulae in R

Model [formulae](http://ww2.coastal.edu/kingw/statistics/R-tutorials/formulae.html) tutorial

- **regression functions in R such as** $aov($ **, lm(), glm(), and** coxph() use a "model formula" interface.
- The formula determines the model that will be built (and tested) by the R procedure. The basic format is:
- > response variable ~ explanatory variables
- **The tilde means "is modeled by" or "is modeled as a function** of."

Regression with a single predictor

Model formula for simple linear regression:

 $> y ~ - x$

- where "x" is the explanatory (independent) variable
- "'y" is the response (dependent) variable.

Return to the spider legs

Friction coefficient for leg type of first leg pair:

```
spider.sub <- spider[spider$leg=="L1", ]
fit <- lm(friction ~ type, data=spider.sub)
summary(fit)
```

```
##
## Call:
## lm(formula = friction ~ type, data = spider.sub)
##
## Residuals:
## Min 1Q Median 3Q Max
## -0.33147 -0.10735 -0.04941 -0.00147 0.76853
##
## Coefficients:
## Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.92147 0.03827 24.078 < 2e-16 ***
## typepush -0.51412 0.05412 -9.499 5.7e-14 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.2232 on 66 degrees of freedom
## Multiple R-squared: 0.5776, Adjusted R-squared: 0.5711
## F-statistic: 90.23 on 1 and 66 DF, p-value: 5.698e-14
```
Regression on spider leg type

Regression coefficients for f riction \sim type for first set of spider legs:

```
fit.table <- xtable::xtable(fit, label=NULL)
print(fit.table, type="html")
```


- How to interpret this table?
	- *Coefficients for (Intercept) and typepush*
	- *Coefficients are t-distributed when assumptions are correct*
	- *Standard Error is the sampling variance of the estimates*

Interpretation of coefficients

Diagram of the estimated coefficients in the linear model. The green arrow indicates the Intercept term, which goes from zero to the mean of the reference group (here the 'pull' samples). The orange arrow indicates the difference between the push group and the pull group, which is negative in this example. The circles show the individual samples, jittered horizontally to avoid overplotting.

Regression on spider leg position

Remember there are positions 1-4

fit <- lm(friction ~ leg, data=spider)

```
fit.table <- xtable::xtable(fit, label=NULL)
print(fit.table, type="html")
```


Interpretation of the dummy variables legL2, legL3, legL4?

Regression with multiple predictors

Additional explanatory variables can be added as follows:

 $>$ y ~ x + z

Note that "+" does not have its usual meaning, which would be achieved by:

 $> y \sim I(x + z)$

Regression on spider leg type and position

Remember there are positions 1-4

fit <- lm(friction ~ type + leg, data=spider)

```
fit.table <- xtable::xtable(fit, label=NULL)
print(fit.table, type="html")
```


this model still doesn't represent how the friction differences between different leg positions are modified by whether it is pulling or pushing

Interaction (effect modification)

Interaction between coffee and time of day on performance

Image credit: <http://personal.stevens.edu/~ysakamot/>

Interaction (effect modification)

Interaction is modeled as the product of two covariates:

 $E[y|x] = \beta_0 + \beta_1x_1 + \beta_2x_2 + \beta_1x_1 * x_2$

Summary: model formulae

Summary: types of standard linear models

 $lm(y - u + v)$

uand vfactors: **ANOVA** uand vnumeric: **multiple regression** one factor, one numeric: **ANCOVA**

- R does a lot for you based on your variable classes
	- *be sure you know the classes of your variables*
	- *be sure all rows of your regression output make sense*

The Design Matrix

The Design Matrix

Recall the multiple linear regression model:

 $y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \ldots + \beta_p x_{pi} + \epsilon_i$

 $\hat{x_{ji}}$ is the value of predictor $\hat{x_j}$ for observation i

The Design Matrix

Matrix notation for the multiple linear regression model:

$$
\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix} = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots \\ 1 & x_N \end{pmatrix} \begin{pmatrix} \beta_0 \\ \beta_1 \end{pmatrix} + \begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_N \end{pmatrix}
$$

or simply:

$$
\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}
$$

- The design matrix is $\mathbf X^{\top}$
	- *which the computer will take as a given when solving for by* β *minimizing the sum of squares of residuals* $\boldsymbol{\varepsilon}$ *.*

Choice of design matrix

- there are multiple possible and reasonable design matrices for a given study design
- the model formula encodes a default model matrix, e.g.:

```
group <- factor( c(1, 1, 2, 2) )
model.matrix(~ group)
```

```
## (Intercept) group2
## 1 1 0
## 2 1 0
## 3 1 1
## 4 1 1
## attr(,"assign")
## [1] 0 1
## attr(,"contrasts")
## attr(,"contrasts")$group
## [1] "contr.treatment"
```
Choice of design matrix

What if we forgot to code group as a factor?

```
group <- c(1, 1, 2, 2)
model.matrix(~ group)
```

```
## (Intercept) group
## 1 1 1
## 2 1 1
## 3 1 2
## 4 1 2
## attr(,"assign")
## [1] 0 1
```
More groups, still one variable

```
group <- factor(c(1,1,2,2,3,3))
model.matrix(~ group)
```


Changing the baseline group

```
group <- factor(c(1,1,2,2,3,3))
group <- relevel(x=group, ref=3)
model.matrix(~ group)
```

```
## (Intercept) group1 group2
## 1 1 1 0
## 2 1 1 0
## 3 1 0 1
## 4 1 0 1
## 5 1 0 0
## 6 1 0 0
## attr(,"assign")
## [1] 0 1 1
## attr(,"contrasts")
## attr(,"contrasts")$group
## [1] "contr.treatment"
```
More than one variable

```
diet <- factor(c(1,1,1,1,2,2,2,2))
sex <- factor(c("f","f","m","m","f","f","m","m"))
model.matrix(~ diet + sex)
```

```
## (Intercept) diet2 sexm
## 1 1 0 0
## 2 1 0 0
## 3 1 0 1
## 4 1 0 1
## 5 1 1 0
## 6 1 1 0
## 7 1 1 1
## 8 1 1 1
## attr(,"assign")
## [1] 0 1 2
## attr(,"contrasts")
## attr(,"contrasts")$diet
## [1] "contr.treatment"
##
## attr(,"contrasts")$sex
## [1] "contr.treatment"
```
With an interaction term

model.matrix(~ diet + sex + diet:sex)

Design matrix to contrast what we want

- **Spider leg friction example:**
	- *The question of whether push vs. pull difference is different in L2 compared to L1 is answered by the term typepush:legL2in a model with interaction terms:*

fitX <- lm(friction ~ type * leg, data=spider)

**What if we want to ask this question for L3 vs L2?

Design matrix to contrast what we want

What if we want to contrast…

typepush:legL3 - typepush:legL2

There are many ways to construct this design, one is with library(multcomp):

```
names(coef(fitX))
```


```
C \leq -\text{ matrix}(c(0,0,0,0,0,-1,1,0), 1)L3vsL2interaction <- multcomp::glht(fitX, linfct=C)
```
Design matrix to contrast what we want

Is there a difference in pushing friction for L3 vs L2?

```
summary(L3vsL2interaction)
```

```
##
## Simultaneous Tests for General Linear Hypotheses
##
## Fit: lm(formula = friction ~ type * leg, data = spider)
##
## Linear Hypotheses:
## Estimate Std. Error t value Pr(>|t|)
## 1 == 0 -0.27988 0.07893 -3.546 0.00046 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## (Adjusted p values reported -- single-step method)
```
Summary: applications of model matrices

- Major differential expression packages recognize them:
	- *LIMMA (VOOM for RNA-seq)*
	- *DESeq2 for all kinds of count data*
	- *EdgeR*
- Can fit coefficients **directly** to your contrast of interest
	- *e.g.: what is the difference between push/pull friction for each spider-leg pair?*

Analysis of Variance

Why Analysis of Variance?

- Analysis of Variance allows inference on the inclusion of a \blacksquare categorical or continuous variable
	- *not just on re-coded "dummy" variables (e.g. for each spider leg pair)*

Friction coefficients of different leg pairs

Compare ANOVA table to regression table

print(xtable::xtable(summary(fit)), type="html")

print(xtable::xtable(anova(fit)), type="html")

 $F = \frac{\text{variability between groups}}{\text{variability within groups}} =$ variability within groups reduction in variance from adding variable variance of residuals

Analysis of Variance: F test

- Compares *between* group variance to *within* group variance \blacksquare
	- $F = \frac{\text{variability between groups}}{\text{variability within groups}} =$ variability within groups reduction in variance from adding variable variance of residuals
- The F distribution depends on both *numerator* (df1) and *denominator* (df2) degrees of freedom
- Rejection region is in the right tail only: \blacksquare

 $df(df1=5, df2=5)$

Summary

- **EXTE:** Linear models are the basis for identifying differential expression / differential abundance
	- *continuous* Y ; any kind of X variables

Assumptions:

- *1. normal, homoscedastic errors,*
- *2. a linear relationship, and*
- *3. independent observations.*
- Note that **t** and **F** tests are *robust* and *conservative* to violations of 1 and 2
	- extremely so for $n > 30$

Summary (cont'd)

- Know the model formula interface, but
	- *use model matrices to directly fit coefficients that you want to interpret*

Generalized Linear Models extend these methods to:

- *binary (logistic regression)* Y
- *count (log-linear regression with e.g. Poisson or Negative Binomial link* Y*functions)*

Links

- A built [html](http://rpubs.com/lwaldron/CSAMA2016_IntroLinearModels) version of this lecture is available.
- **The [source](https://github.com/waldronlab/presentations/tree/master/Waldron_2016-07-11_CSAMA_linearmodels) R Markdown is also available from Github.**